REMARKS

Entry of the amendments to the specification, claims and abstract before examination of the application is respectfully requested. These claims have been amended to remove multiple dependencies and these claims patentably define over the art of record.

If there are any questions regarding this Preliminary Amendment or the application in general, a telephone call to the undersigned would be appreciated since this should expedite the prosecution of the application for all concerned.

If necessary to effect a timely response, this paper should be considered as a petition for an Extension of Time sufficient to effect a timely response, and please charge any deficiency in fees or credit any overpayments to Deposit Account No. 05-1323 (Docket # 028987.56522US).

Respectfully submitted,

September 20, 2006

James F. McKeown Registration No. 25,406

CROWELL & MORING LLP Intellectual Property Group P.O. Box 14300 Washington, DC 20044-4300 Telephone No.: (202) 624-2500

Facsimile No.: (202) 628-8844

JFM:aw

2789387

IAP16 Rec'd PCT/PTO 20 SEP 2006 10/593495

IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

Application No. : To Be Assigned Confirmation No. : To Be Assigned

First Named Inventor : Peter BAUR

Filed : September 20, 2006

TC/A.U. : To Be Assigned
Examiner : To Be Assigned
Docket No. : 028987.56522US

Customer No. : 23911

Title : Hydraulic Linear Drive, Particularly a Hydraulic

Transmission Actuator

SUBMISSION OF SUBSTITUTE SPECIFICATION

Commissioner for Patents P.O. Box 1450 Alexandria, VA 22313-1450

Sir:

Attached are a Substitute Specification and a marked-up copy of the original specification. I certify that said substitute specification contains no new matter and includes the changes indicated in the marked-up copy of the original specification.

Respectfully submitted,

September 20, 2006

James F. McKeown Registration No. 25,406

CROWELL & MORING LLP Intellectual Property Group P.O. Box 14300 Washington, DC 20044-4300 Telephone No.: (202) 624-2500 Facsimile No.: (202) 628-8844

JFM:qng

IAP16 Rec'd PCT/PTO 20 SEP 2006 10/593495

Attorney Docket No. 028987.56522US Marked-up Substitute Specification

HYDRAULIC LINEAR DRIVE, PARTICULARLY A HYDRAULIC TRANSMISSION
ACTUATOR

BACKGROUND OF THE INVENTION

-1"

The <u>present</u> invention relates to a hydraulic linear drive, particularly a hydraulic transmission actuator, according to the characteristics of the preamble of Claim 1 in which an actuating piston longitudinally displaceably arranged in the cylinder housing in the cylinder space into at least two pressure chambers which can be acted upon by hydraulic oil by way of control conduits, and having a piston rod connected with the actuating piston, as well as having a scaling element arranged on the actuating piston, by means of which scaling element, the at least two pressure chambers are scaled off from one another.

Hydraulic linear drives are used, for example, in the case of automated standard transmissions, for the synchronization of the transmission gears (see, for example, Johannes Loomann, "Zahnradgetriebe", 2nd Edition, Page 156, and on).

In the case of the hydraulic linear drives of the abovementioned type, the dual piston bounded by two pressure chambers
is in each case pushed toward the left or right as a result of
correspondingly being acted upon by pressure. In many of the
application cases, the two pressure chambers are sealed off by
sealing elements arranged on the outer circumference of the
piston.

Particularly in the case of hydraulic transmission actuators, high actuating forces are applied during the synchronization of the transmission gears, which and require a reliable and durable sealing-off or separation of the two pressure chambers.

SUMMARY OF THE INVENTION

It is therefore an An object of the present invention to improve the sealing-off of the two pressure chambers in the area of the piston unit. This object [[is]] has been achieved by means of the characteristics indicated in Claim 1. As a result of the fact that the actuating piston is constructed in two parts and a sealing element is arranged between the two piston parts. The [[, the]] sealing element is clamped between the two piston parts when the piston unit is adjusted and, because of the actuating forces to be applied, for example, during the

synchronization of the transmission gear, is pressed radially toward the outside to a certain extent. Thereby, so that the sealing between the actuating piston and the interior cylinder wall is advantageously improved.

By means of the characteristics indicated in the subclaims, additional advantageous embodiments and further developments of the hydraulic linear drive can be obtained.

The sealing element constructed as a sealing ring is received on a sealing device carrier which is axially guided on one of the two piston parts.

For a better axial guidance of the sealing device carrier, the latter engages on the face in the first piston part.

The sealing device carrier is shaped in one piece out of one of the two piston parts or, as an alternative, is arranged as a separate component between the two piston parts.

The sealing device carrier is advantageously longitudinally displaceably disposed on the first piston part, for limiting the contact pressure force exercised upon the sealing ring. The [[,

the]] relative movement of the sealing device carrier [[being]] is limited by two stops constructed on the first piston part.

An advantageous embodiment of a hydraulic linear drive which is adapted to the use as a hydraulic transmission actuator is obtained when the two piston parts and the cylinder housing have a stepped construction. As a result of the step piston which is forming provides in this manner, in a first adjusting path, a high adjusting speed can be achieved with a low friction. Because while, because of a large piston diameter, a high actuating force can be generated about the synchronization point and thus a high radial contact pressure force of the sealing ring against the interior wall of the cylinder housing.

A longitudinal groove is formed in the surface area of the piston part section having a reduced diameter. The, which longitudinal groove in each case connects a first hydraulic chamber section with a second hydraulic chamber section of the two step pistons.

One control conduit respectively is connected to the two first hydraulic chamber sections of the two step pistons, which control conduit is used for the feeding or removal of hydraulic oil. Other objects, advantages and novel features of the present invention will become apparent from the following detailed description of the invention when considered in conjunction with the accompanying drawings.

BRIEF DESCRIPTION OF THE DRAWINGS

Two embodiments of the invention are illustrated in the drawing and will be described in detail in the following.

Figure 1 is a <u>partial cross-sectional</u> view of a [[liner]]

<u>linear drive with a <u>schematically shown</u> hydraulic control

according to a first embodiment of the present invention; and</u>

Figure 2 is a <u>partial cross-sectional view of a linear</u> drive having a hydraulic control according to a second embodiment of the invention.

DETAILED DESCRIPTION OF THE INVENTION

The hydraulic linear drive, which is illustrated in Figure 1 [[and]] can be used, for example, as a hydraulic transmission actuator for an automated standard transmission. The drive[[,]] has a two-part cylinder housing 2a, [[and]] 2b, which parts are both mutually connected, preferably screwed together, on their faces. In the cylinder space formed by the cylinder housing 2a,

<u>2b</u>, two piston parts are received which are called step pistons 4. [[and]] 6 in the following are received and, both being equipped with one piston rod 8. [[and]] 10 respectively guided out of the cylinder housing 2, are longitudinally displaceably guided in the cylinder housing 2. In this case, the sealing-off of each of the two pistons rods 8. [[and]] 10 takes place by means of one respective sealing ring 12. [[and]] 14 respectively. The two step pistons 4. [[and]] 6 each have two piston sections 4a, 4b and 6a, 6b respectively, in which [[case]] a sealing device carrier 18 with a sealing ring 16 is arranged between the mutually facing faces of the pistons section 4b. [[and]] 6b provided with a larger diameter.

The sealing device carrier 18 is disposed on an interior ring flange section 20 of the piston section 4b and, on its right face, is screwed to the piston section 6b of the step piston 6, while, on its left face, it engages by [[means]] way of a ring flange 22 in a gearing manner in a ring groove 24 constructed between a central ring flange section 23 and an outer ring flange section 25 of the piston section 4b. The sealing ring 16 is pushed onto the ring flange 22 and correspondingly seals off the two pressure chambers 26, [[and]] 28 from one another which are separated by the step pistons 4, [[and]] 6.

For limiting the sealing device carrier 18 longitudinally displaceably disposed on the interior ring flange section 20, a left and a right stop is provided. The[[, the]] left stop [[being]] is formed by the central ring flange section 23 of the piston section 4b, and the right step 32 [[being]] is formed by a limit stop washer 32a which is axially secured by a snap ring 32b received in a ring groove. Further, a flat coil spring 34, which is arranged on the interior ring flange section 20, is accommodated in a ring groove forming between the interior and central ring flange section 20, [[and]] 23 and is therefore clamped in between the sealing device carrier 18 and the piston section 4b.

The <u>surface area of the</u> two piston sections 4a, [[and]] 6a respectively [[have]] has a respective longitudinal groove 36, [[and]] 38 made in the surface area, which longitudinal groove 36 and 38 respectively each of which hydraulically connects the respective pressure chamber 26, [[and]] 28 respectively with a respective second pressure chamber 40, [[and]] 42 respectively. The two pressure chambers 40, [[and]] 42, in the following ealled namely, first pressure chambers, are bounded in each case by the respective face 41, [[and]] 42 respectively of the piston section 4a, [[and]] 6a and the face of the respective sealing

ring 12, [[and]] 14 respectively. One hydraulic conduit 44, [[and]] 46 respectively is connected to the two first pressure chambers 40, [[and]] 42, by way of which hydraulic conduit 44 and 46, so that by [[means]] way of a 7/2-way control valve 48, [[these]] the pressure chambers 40, 42 can optionally be supplied with hydraulic oil from a tank 50. One return flow conduit 49, [[and]] 51 is in each case connected to the respective two pressure chambers 26, [[and]] 28, respectively, in the following, called namely, second pressure chambers. The which return flow conduit 49, [[and]] 51 can optionally be connected by way of the control valve 48 with the tank 50.

In the following, the method of operation of the hydraulic linear drive will be described in the following:

In the control position of the 7/2-way valve 48 illustrated in Figure 1, the first pressure chamber 42 is acted upon by hydraulic oil by [[way of]] the hydraulic conduit 46 for the displacement of the two step pistons 4, [[and]] 6 toward the left. By means of the The actuating force exercised on the face 43 of the piston section 6a[[,]] displaces the piston unit consisting of the two step pistons 4, [[and]] 6 is displaced toward the left. In that , in which case, after a first adjusting path, by way of the longitudinal groove 38 connecting

the two pressure chambers 42, [[and]] 28, the second pressure chamber 28 is also filled with hydraulic oil.

After moving a further distance, the hydraulic oil arrives in an unthrottled manner from the first pressure chamber 42 in the second pressure chamber 28 and acts exclusively with respect to the piston section 6b with the larger diameter. Thus, so-that, on the one hand, the adjusting rate of the actuating piston 4, 6 is reduced but, on the other hand, the actuating force acting upon the step piston 6 is increased. Simultaneously, the hydraulic oil situated in the first and second pressure chamber 40, [[and]] 26 of the opposite side is returned into the tank 50 by [[way of]] the return conduit 49 and the hydraulic conduit 44. fact that the piston unit 4, 6 is displaced against a resistance, has the effect that the sealing ring 16 clamped in between the exterior ring flange section 25 of the piston section 4b and the sealing device carrier 18 deforms elastically and is thereby pressed radially against the interior wall of the cylinder housing 2.

The hydraulic linear drive can be used, for example, as a hydraulic transmission actuator, in which case a shift fork engaging in a gearshift sleeve unit is axially displaced by means—of the transmission actuator for establishing a non-rotatable connection between the gearshift sleeve and the

transmission gear. In [[this] <u>such</u> case, a high adjusting speed with a low friction is reached by way of a first adjusting path <u>by means of via</u> the two piston sections 4a, [[and]] 6a respectively which have the smaller diameter, while about the synchronization point, a high radial contact pressure force of the sealing ring 16 can be achieved with respect to the interior cylinder wall <u>by means of via</u> the two piston sections 4b, [[and]] 6b respectively which have a larger diameter.

p.1 1.1

The second embodiment of the hydraulic linear drive illustrated in Figure 2 differs from that of Figure 1 only with respect to the hydraulic control. Instead of the [[7/2]] 7/2-way control valve 48 used in the first embodiment, the controlling of the feeding and removal of hydraulic oil now takes place by way of a first 4/2 control valve 56 and a second 3/2 control valve 58. By way of the first 4/2 control valve 56, the two first pressure chambers 40, [[and]] 42 respectively can optionally be acted upon by hydraulic oil, while the return of the hydraulic oil from the first two pressure chambers 26, [[and]] 28 respectively is controlled by the control valve 58. The difference with respect to the first embodiment consists of the fact that, by the respective closing of the conduit 49, [[and]] 51, the hydraulic oil to be returned from the respective second pressure chamber 26, [[and]] 28 into the tank 50 is returned in this second

embodiment by way of the longitudinal groove 36, [[and]] 38
respectively, the respective first pressure chamber 40,
[[and]] 42 respectively and the respective hydraulic conduit
44, [[and]] 46 respectively. As a result, an additional
damping of the adjusting movement can be achieved,
particularly when reaching one of the two end positions of the
actuating piston pistons 4, 6.